

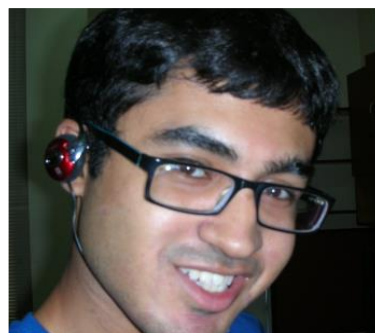
Iterative Hard Thresholding for Sparse/Low-rank Linear Regression

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Our work

- Foundations
- Systems
- Applications
- Interplay of society and technology
- Academic and government outreach

Our vectors of impact

- Research impact
- Company impact
- Societal impact

Machine Learning and Optimization @ MSRI

- High-dimensional Learning & Optimization
- Extreme Classification
- Online Learning / Multi-armed Bandits

We are Hiring!

- Interns
- PostDocs
- Applied Researchers
- Full-time Researchers

- Ranking & Recommendation

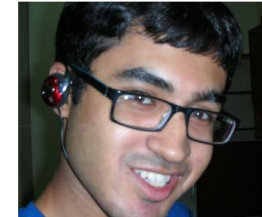
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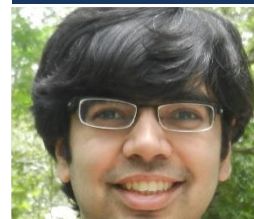
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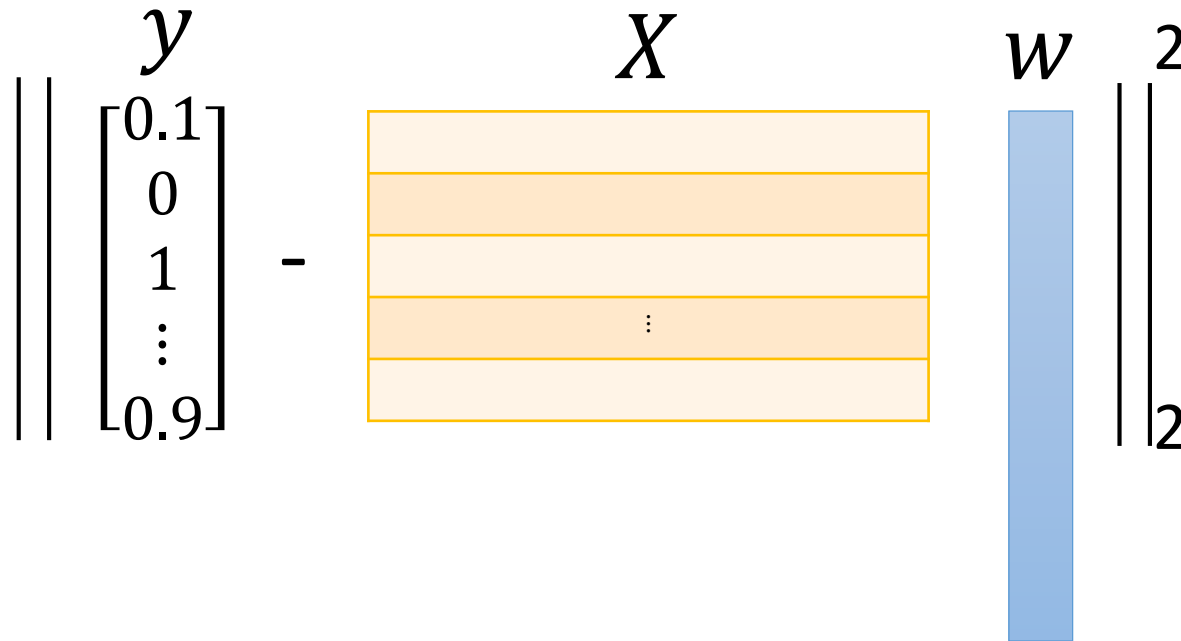
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Learning in High-dimensions



- Need to solve: $\min_w ||y - Xw||_2^2$ s.t. $w \in C$

- C can be:

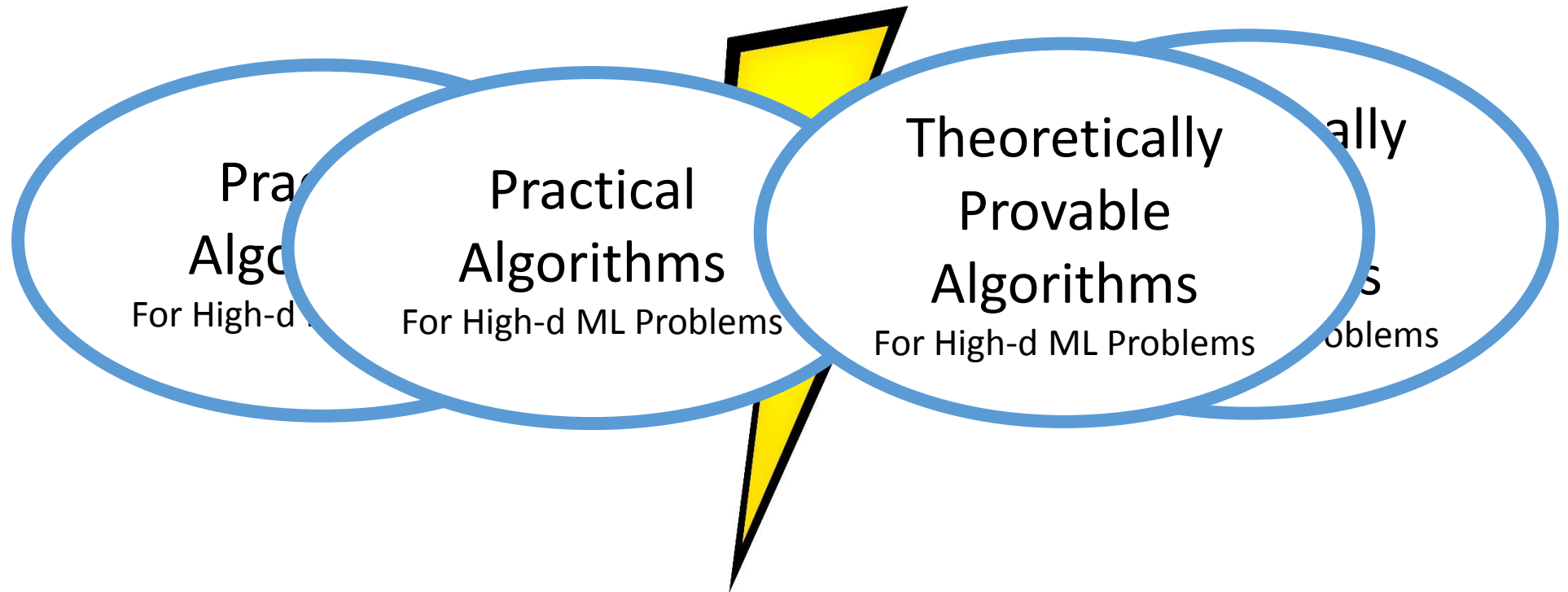
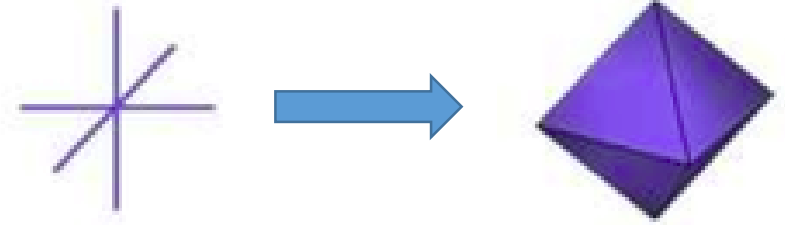
- Set of sparse vectors
- Set of group-sparse vectors
- Set of low-rank matrices



- Non-convex
- Comp. Complexity: NP-Hard

Overview

- Most popular approach: convex relaxation
 - Solvable in poly-time
 - Guarantees under certain assumptions
 - **Slow in practice**



Results

- Sparse Regression [[Garg & Khandekar. ICML 2008](#); [J., Kar, Tewari. NIPS14](#)]
 - L_0 – constraint
- Matrix Completion/Regression [[J., Netrapalli, Sanghavi. STOC 2013](#); [Hardt & Wooters. COLT 2014](#)]
 - Low-rank constraint
- Robust Regression [[Loh & Wainwright. NIPS 2013](#) ; [Bhatia, J., Kar. Submitted, 2015](#)]
- Tensor Factorization and Completion [[Anandkumar et al. Arxiv 2012](#); [J., Oh. NIPS14](#)]
 - Low-tensor rank constraint
- Dictionary Learning [[Agarwal et al. COLT 2014](#); [Arora et al. COLT 2014](#)]
 - Non-convex bilinear form + Sparsity constraint
- Phase Sensing [[Netrapalli, J., Sanghavi. NIPS13](#) ; [Candes et al. Arxiv'2014](#)]
 - System of quadratic equations
- Low-rank matrix approximation [[Bhojanapalli, J., Sanghavi. SODA15](#)]

Outline

- Sparse Linear Regression
 - Lasso
- Iterative Hard Thresholding
 - Our Results
- Low-rank Matrix Regression
- Low-rank Matrix Completion
- Conclusions

Sparse Linear Regression

$$\begin{aligned} & \min_w ||y - Xw||^2 \\ & \text{s.t. } ||w||_0 \leq s \end{aligned}$$

- $||y - Xw||^2 = \sum_i (y_i - \langle x_i, w \rangle)^2$
- $||w||_0$: number of non-zeros
- NP-hard problem in general ☹
 - L_0 : non-convex function

Convex Relaxation

$$\begin{aligned} \min_w & \|y - Xw\|^2 \\ \text{s.t.} & \|w\|_0 \leq s \end{aligned}$$

- Relaxed Problem:

$$\begin{aligned} \min_w & \|y - Xw\|^2 \\ \text{s.t.} & \|w\|_1 \leq \mu(s) \end{aligned}$$



$$\min_w \|y - Xw\|^2 + \lambda \|w\|_1$$

Lasso Problem

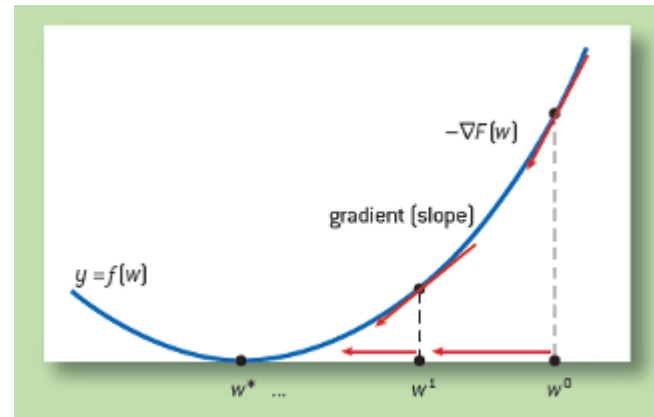
Non-differentiable

- $\|w\|_1 = \sum_i |w_i|$
 - Known to promote sparsity
- Pros: a) Principled approach, b) Solid theoretical guarantees
- Cons: Slow to optimize

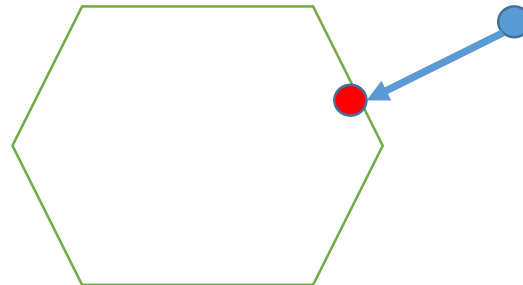
Our Approach : Projected Gradient Descent

$$\min_w f(w) = \|y - Xw\|^2$$
$$s.t. \|w\|_0 \leq s$$

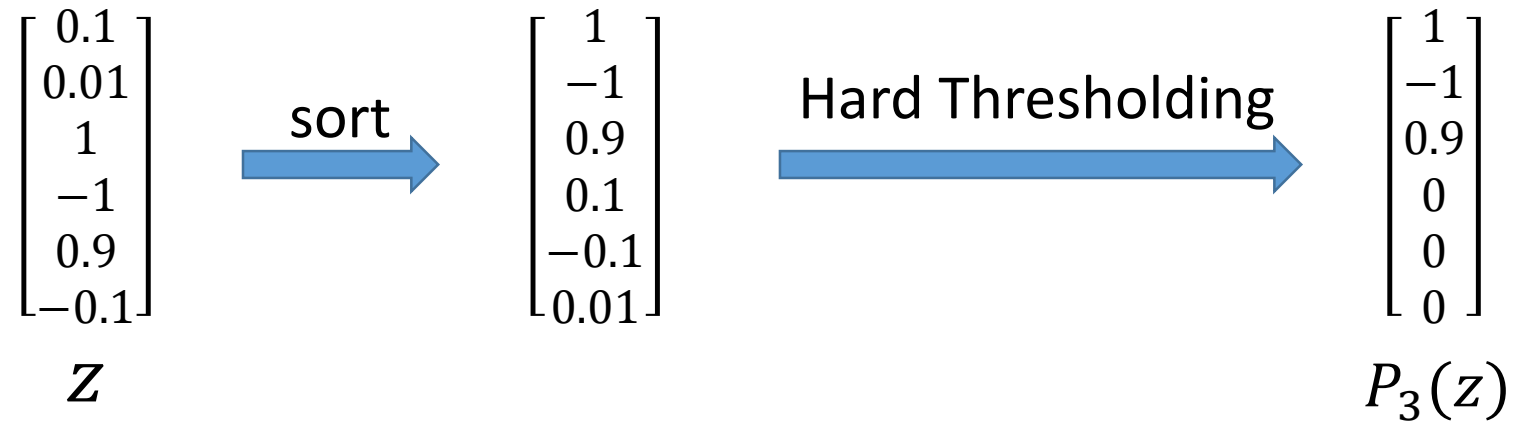
- $w_{t+1} = w_t - \partial_{w_t} f(w_t)$



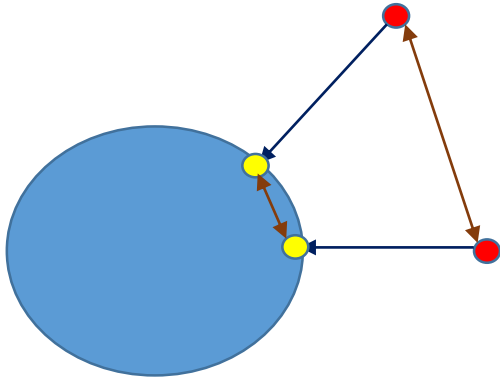
- $w_{t+1} = P_S(w_{t+1})$



Projection onto L_0 ball?



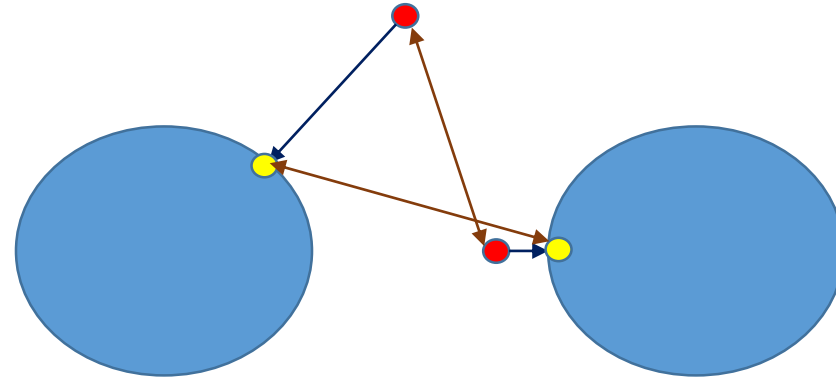
Convex-projections vs Non-convex Projections



$$\|P_C(a) - P_C(b)\| \leq \|a - b\|$$

C : convex set

1st order Optimality condition



$$\|P_C(a) - a\| \leq \|u - a\|, \quad \forall u \in C$$

C : non-convex set

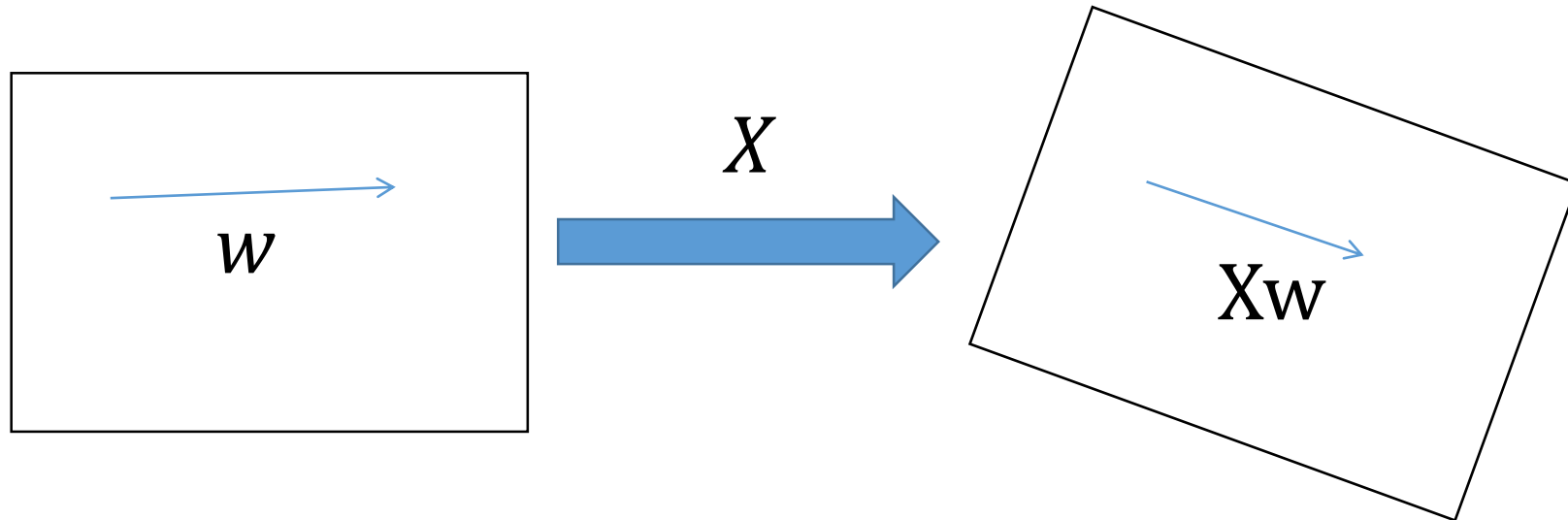
0-th order Optimality condition

- 0 order condition sufficient for convergence of Proj. Grad. Descent?
- In general, **NO** 😞
- But, for certain *specially structured* problems, **YES!!!**

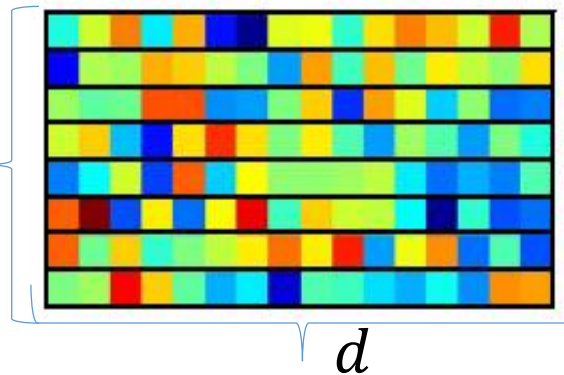
Restricted Isometry Property (RIP)

- X satisfies RIP if, for all **sparse** vectors X acts as an Isometry
- Formally: For all s -sparse \mathbf{w}

$$(1 - \delta_s) \|\mathbf{w}\|^2 \leq \|X\mathbf{w}\|^2 \leq (1 + \delta_s) \|\mathbf{w}\|^2$$



Popular RIP Ensembles

$$n = O\left(\frac{s}{\delta_s^2} \log \frac{d}{s}\right)$$


X

- Most popular examples:
 - $X_{ij} \sim N(0, 1/\sqrt{n})$
 - $X_{ij} = +\frac{1}{\sqrt{n}}$ (w.p. $\frac{1}{2}$) and $-\frac{1}{\sqrt{n}}$ (w.p. $\frac{1}{2}$)

Proof under RIP

Assume: $y = Xw^*$, $\min_{w, \|w\|_0 \leq s} f(w) = \|y - Xw\|^2 = \|X(w - w^*)\|^2$

Recall: $w_{t+1} = P_S(w_t - X^T X(w_t - w^*))$

Hard
Thresholding

$$\|w_{t+1} - (w_t - X^T X(w_t - w^*))\| \leq \|w^* - (w_t - X^T X(w_t - w^*))\|$$

$I: \text{supp}(w_t) \cup \text{supp}(w_{t+1}) \cup \text{supp}(w^*)$, $|I| \leq 3s$

$$\|w_{t+1} - (w_t - X_I^T X_I(w_t - w^*))\|^2 \leq \|w^* - (w_t - X_I^T X_I(w_t - w^*))\|^2$$

Triangle inequality

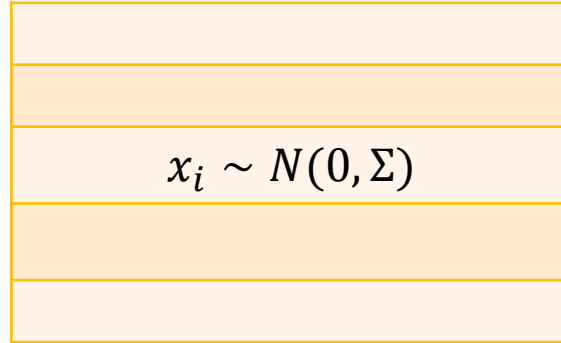
$$\begin{aligned} \|w_{t+1} - w^*\| &\leq 2\|(I - X_I^T X_I)(w_t - w^*)\| \\ &\leq 2\delta_{3s}\|w_t - w^*\| \end{aligned}$$

RIP

What if RIP is not possible?

- $y_i = \langle x_i, w^* \rangle$

- $x_i \sim N(0, \Sigma)$



$$\Sigma = \begin{bmatrix} 1 & 1 - \epsilon & 0 \\ 1 - \epsilon & 1 & 0 \\ 0 & 0 & I_{d-2 \times d-2} \end{bmatrix}$$

- Eigenvalues of $\Sigma = 2 - \epsilon, \epsilon$
- $\delta_s \geq \delta_2 = 1 - \epsilon$
- So, $\delta_s < \frac{1}{2}$ doesn't hold even for infinite samples
 - Problem is solvable for $O(d)$ samples using standard regression

Iterative Hard Thresholding: Larger Sparsity

- $w_1 = 0$
- For $t=1, 2, \dots$
 - $w_{t+1} = P_{s'}(w_t - \eta \nabla_w f(w_t))$
- $s' \geq s$

Stronger Projection Guarantee

$$\|P_{s'}(z) - z\|_2^2 \leq \frac{d - s'}{d - s} \|P_s(z) - z\|_2^2$$

- d : dim of z
- $s \leq s'$

Statistical Guarantees

$$\min_w f(w) = \|y - Xw\|^2$$

Statistically: $n \geq \frac{\sigma^2 \cdot s \log d}{\epsilon^2}$

Known Computation Lower-bound: $\frac{\kappa \cdot \sigma^2 \cdot s \log d}{\epsilon^2}$

Same as Lasso

- w^* : s -sparse

$$\|\hat{w} - w^*\| \leq \epsilon,$$

$$n \geq \frac{\kappa^2 \cdot \sigma^2 \cdot s \log d}{\epsilon^2}$$

- $\kappa = \lambda_1(\Sigma) / \lambda_d(\Sigma)$
- Recall, $w_{t+1} = P_{s'}(w_t - \eta \nabla_w f(w))$
 - $s' = \kappa^2 s$

General Result for Any Function

- $f: R^d \rightarrow R$
- f : satisfies RSC/RSS, i.e.,

$$\alpha_s \cdot I_{d \times d} \preceq H(w) \preceq L_s \cdot I_{d \times d}, \quad \text{if } \|w\|_0 \leq s$$

- IHT guarantee: $f(w_T) \leq f(w^*) + \epsilon$

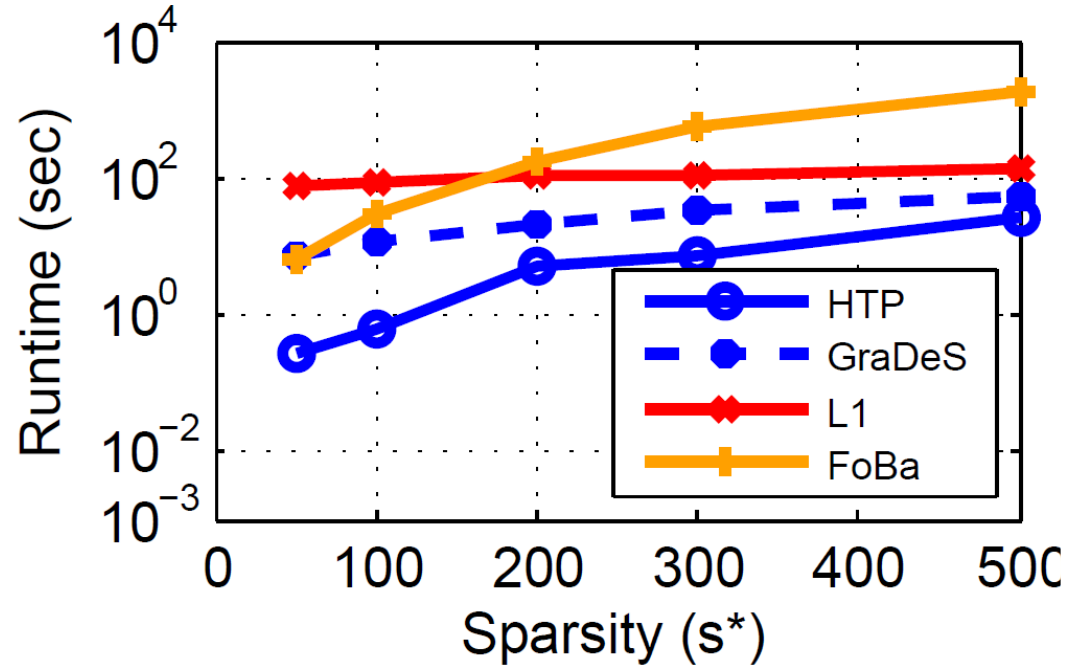
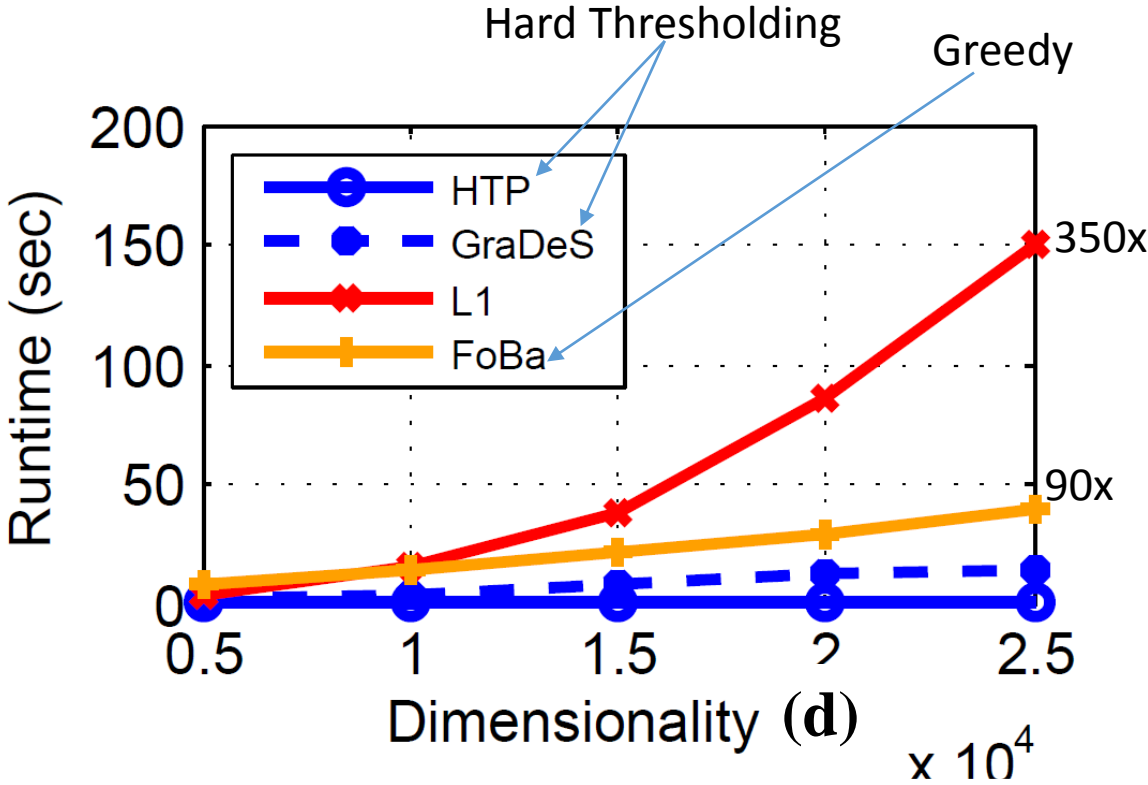
After $T = O\left(\frac{\log\left(\frac{f(w^0)}{\epsilon}\right)}{\log\left(1 - \frac{L_{s'}}{\alpha_{s'}}\right)}\right)$ steps

- If $\|w^*\|_0 \leq s$ and $s' \geq 10 \frac{L_{s'}^2}{\alpha_{s'}} s$

Extension to other Non-convex Procedures

- IHT-Fully Corrective
 - HTP [Foucart'12]
- CoSAMP [Tropp & Neadell'2008]
- Subspace Pursuit [Dai & Milenkovic'2008]
- OMPR [J., Tewari, Dhillon'2010]
- Partial hard thresholding and two-stage family [J., Tewari, Dhillon'2010]

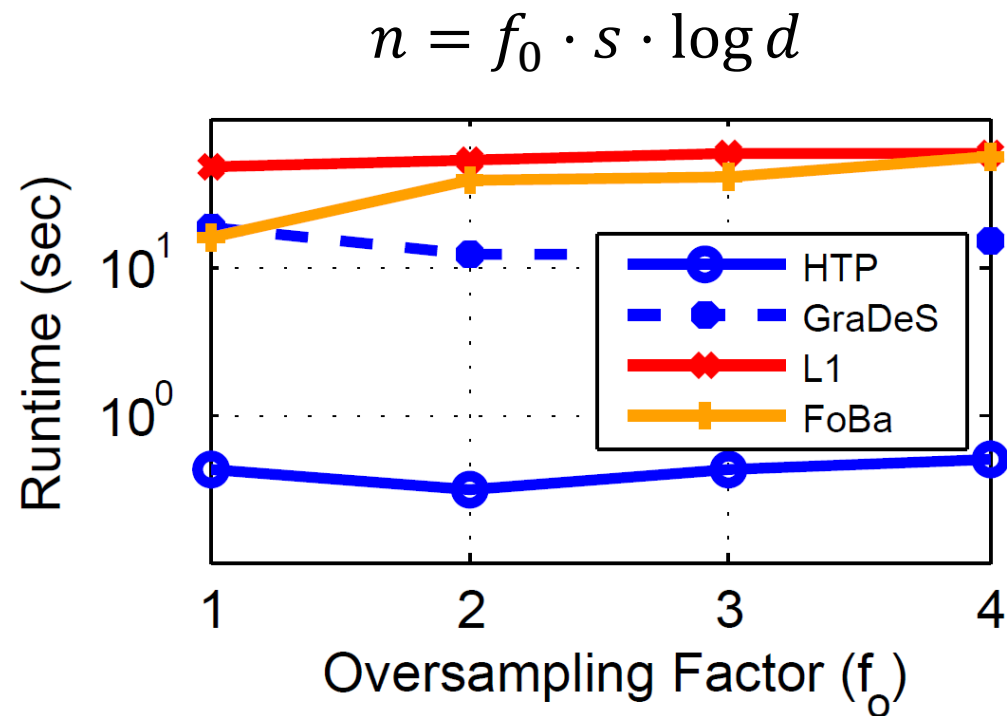
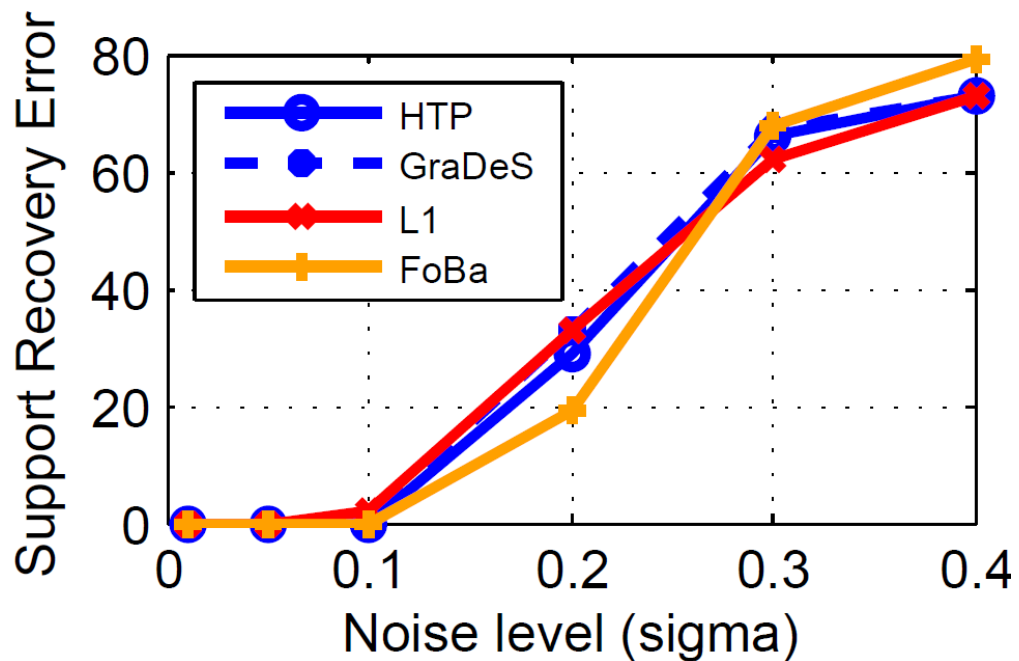
Empirical Results



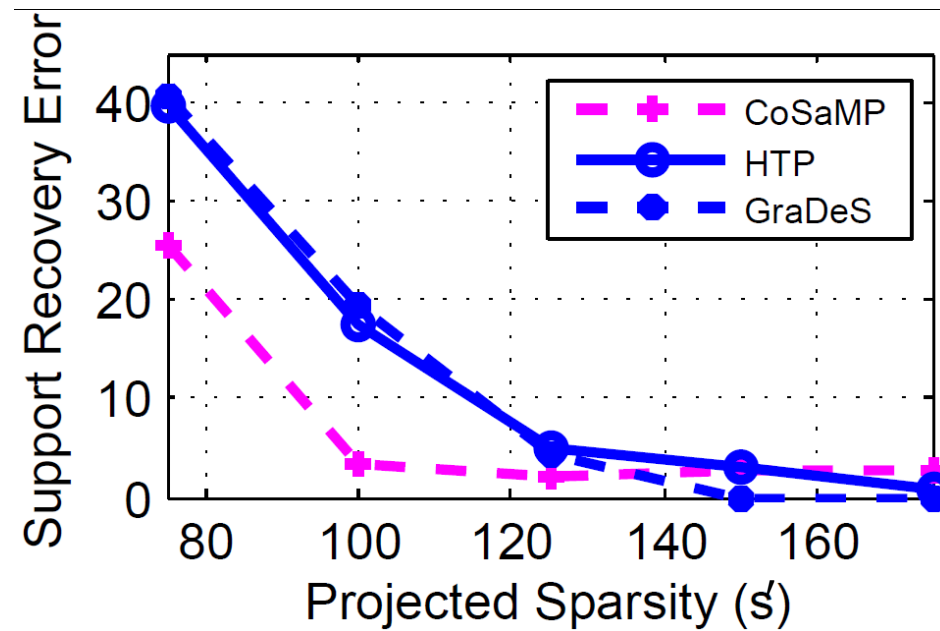
$n = 2 \cdot s \cdot \log(d), s = 300, \kappa = 1$

$n = 2 \cdot s \cdot \log(d), d = 20,000, \kappa = 1$

More Empirical Results



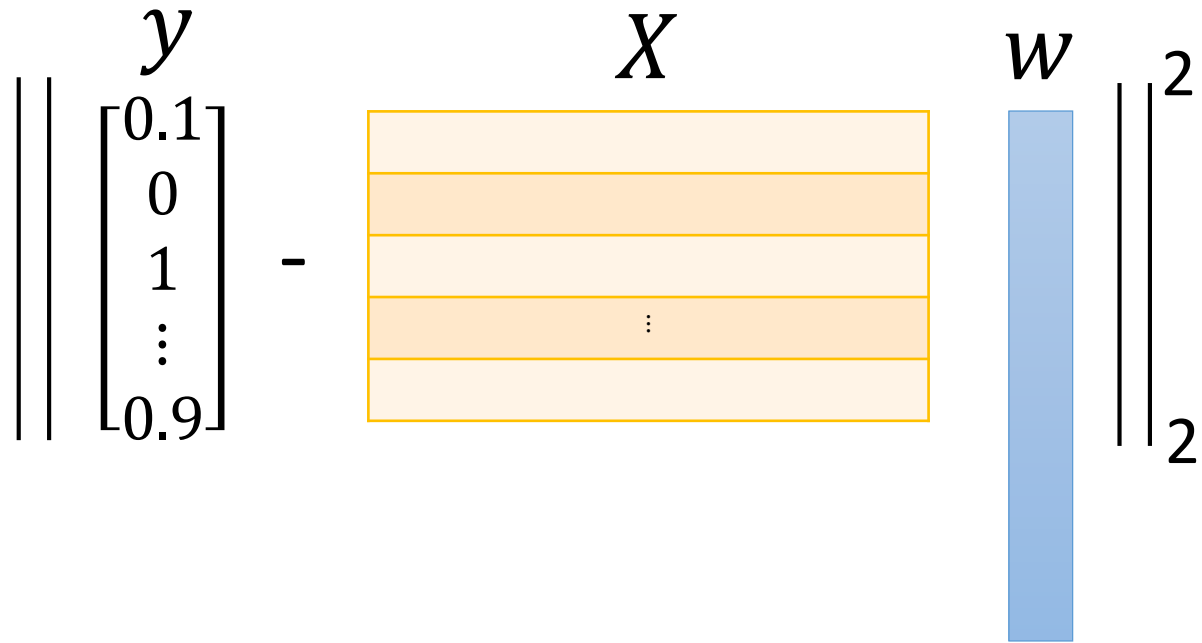
Empirical Results: poor condition number



$$n = 2 \cdot s \cdot \log(d), s = 50, d = 20,000$$

$$\kappa = 50$$

Low-rank Matrix Regression



- W : $d_1 \times d_2$ matrix
- $\text{rank}(W) = r \ll \min(d_1, d_2)$

Low-rank Matrix Regression

$$\min_W f(W) = \|y - X \cdot W\|^2$$
$$s.t. \text{rank}(W) \leq r$$

- Convex relaxation: $\text{rank}(W) \Rightarrow \|W\|_*$
 - $\|W\|_*$ = sum of singular values of W
 - Several interesting results: [\[Recht et al.'2007, Negahban et al'2009\]](#)...
- Projected Gradient Descent:
 - $W_{t+1} = P_k(W_t - \eta \nabla_W f(W_t)), \forall t$
 - $k \geq r$
- $P_k(Z) = U_k \Sigma_k V_k^T$ where $Z = U \Sigma V^T$

Statistical Guarantees

$$y_i = \langle x_i, W^* \rangle + \eta_i$$



- $x_i \sim N(0, \Sigma) \in R^d$
- $\eta_i \sim N(0, \sigma^2)$
- $W^* \in R^{d_1 \times d_2}$, $\text{rank}(W^*) = r$

$$\|\widehat{W} - W^*\|_2 \leq \frac{\sigma \cdot \kappa \cdot \sqrt{r(d_1 + d_2) \log(d_1 + d_2)}}{\sqrt{n}}$$

- $\kappa = \frac{\lambda_1(\Sigma)}{\lambda_d(\Sigma)}$, $k = \kappa^2 r$

Low-rank Matrix Completion

		users											
		1	2	3	4	5	6	7	8	9	10	11	12
movies	1	1		3			5			5		4	
	2			5	4			4			2	1	3
	3	2	4		1	2		3		4	3	5	
	4		2	4		5			4			2	
	5			4	3	4	2					2	5
	6	1		3		3			2			4	

 - unknown rating  - rating between 1 to 5

$$\min_W \sum_{(i,j) \in \Omega} (W_{ij} - M_{ij})^2$$

s. t **rank**(W) $\leq r$

Ω : set of known entries

- Special case of low-rank matrix regression
- However, assumptions required by the regression analysis not satisfied

Guarantees

- Projected Gradient Descent:
 - $W_{t+1} = P_r(W_t - \eta \nabla_W f(W_t)), \quad \forall t$
- Show ϵ -approximate recovery in $\log \frac{1}{\epsilon}$ iterations
- Assuming:
 - M : incoherent
 - Ω : uniformly sampled
 - $|\Omega| \geq n \cdot r^5 \cdot \log^3 n$
- First near linear time algorithm for **exact** Matrix Completion with finite samples

Tale of two Lemmas

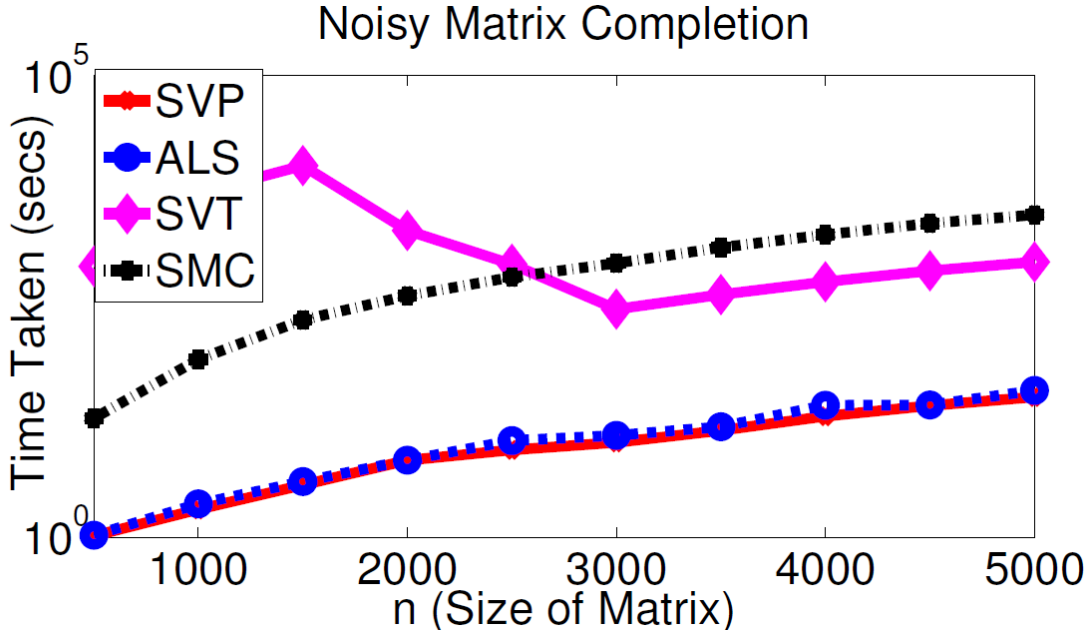
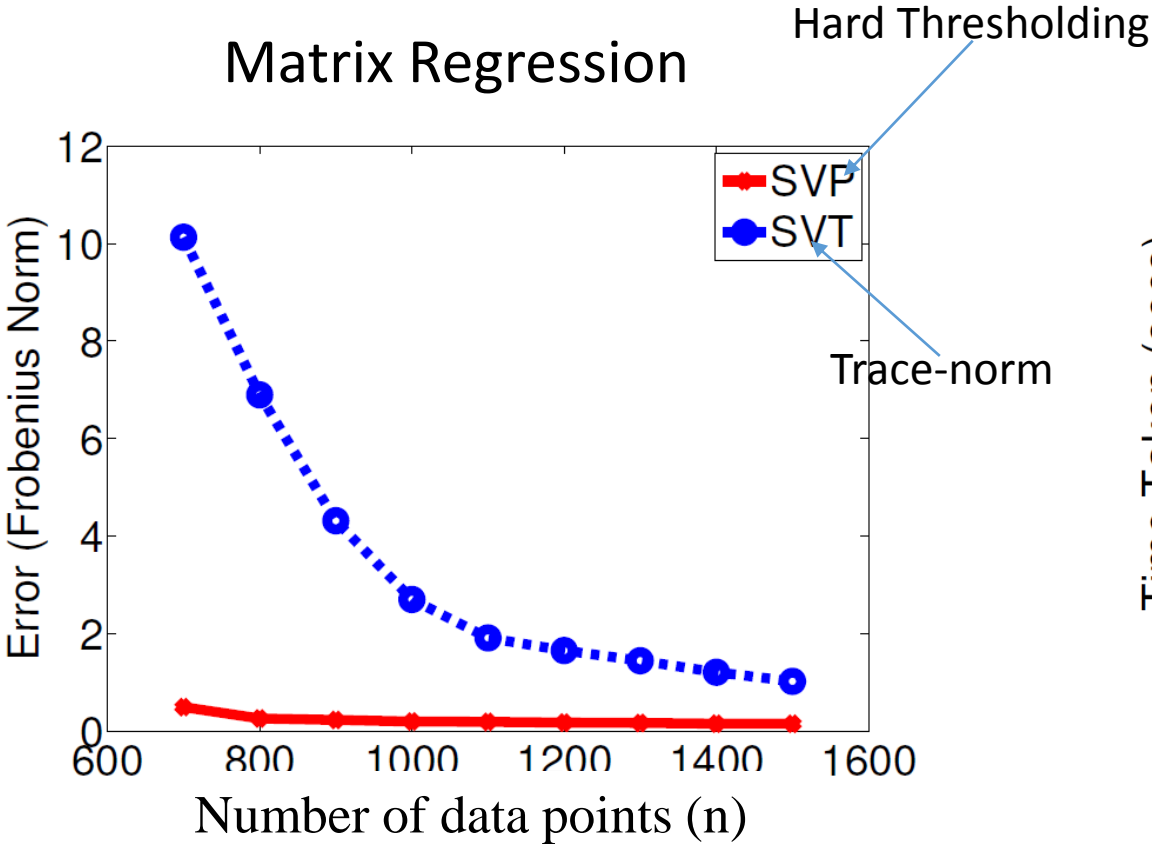
- Lemma 1: Perturbation bound with L_∞ bounds

$$\|P_r(M + E_t) - M\|_\infty \leq .5 \|E_t\|_\infty$$

- Standard bounds only give: $\|P_r(M + E_t) - M\|_2 \leq 2\|E_t\|_2$
 - M : incoherent
 - E_t : zero-mean with small variance
- Lemma 2: Davis-Kahn style result for matrix perturbation
 - If $\sigma_{k+1}(M) < .25 \sigma_k(M)$ and $\|E_t\|_F \leq .25 \sigma_k(M)$

$$\|P_k(M + E_t) - P_k(M)\|_F \leq c(\sqrt{k} \|E_t\|_2 + \|E\|_F)$$

Empirical Results



$$r = 100, |\Omega| = 5 r n \log n$$

Summary

- High-dimensional problems
 - $n \ll d$
- Need to impose structure on w
- Typical structures
 - Sparsity
 - Low-rank
 - Low-rank+Sparsity
- Non-convex sets but easy projection
- Proof of convergence (linear rate)
 - Under suitable generative model assumptions

Future Work

- Generalized theory for such provable non-convex optimization
- Performance analysis on different models
- Empirical comparisons on “real-world” datasets

Questions?